Advanced Microprocessor Notes

Differences between a Microprocessor and a Microcontroller

A microprocessor (abbreviated as μP or uP) is a computer electronic component made from miniaturized transistors and other circuit elements on a single semiconductor integrated circuit (IC) (microchip or just chip). The central processing unit (CPU) is the most well known microprocessor, but many other components in a computer have them, such as the Graphics Processing Unit (GPU) on a video card. In the world of personal computers, the terms microprocessor and CPU are used interchangeably. At the heart of all personal computers and most workstations sits a microprocessor. Microprocessors also control the logic of almost all digital devices, from clock radios to fuel-injection systems for automobiles.

Microcontroller is a computer-on-a-chip optimised to control electronic devices. It is designed specifically for specific tasks such as controlling a specific system. A microcontroller (sometimes abbreviated μC, uC or MCU) is basically a specialized form of microprocessor that is designed to be self-sufficient and cost-effective. Also, a is basically a specialized form of microprocessor that is designed to be self-sufficient and cost-effective. Also, a microcontroller is part of an embedded system, which is essentially the whole circuit board. An embedded microcontroller is part of an embedded system one or a few dedicated functions often with real-time system is a computer system designed to perform one or a few dedicated functions often with real-time computing constraints. It is embedded as part of a complete device often including hardware and mechanical parts.

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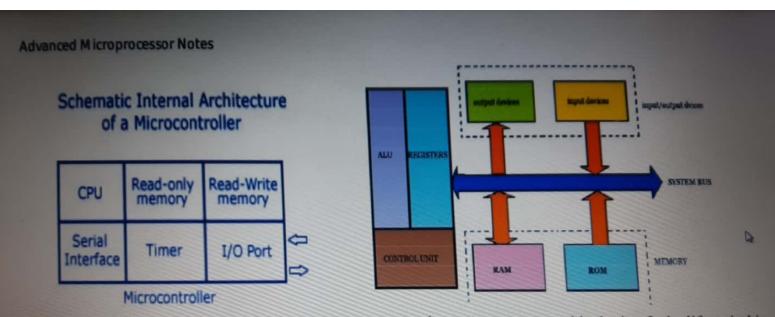
- The CPU core (microprocessor)
- Memory (both ROM and RAM)
- · Some parallel digital I/O

The microcontroller sees the integration of a number of useful functions into a single IC package. These functions are:

- The ability to execute a stored set of instructions to carry out user defined tasks.
- The ability to be able to access external memory chips to both read and write data from and to the memory.

The difference between the two is that a microcontroller incorporates features of microprocessor (CPU, ALU, Registers) along with the presence of added features like presence of RAM, ROM, I/O ports, counter, etc. Here a microcontroller controls the operation of a machine using fixed programs stored in ROM that doesn't change with lifetime.

From another view point, the main difference between a typical microprocessor and a micro controller leaving there architectural specifications is the application area of both the devices. Typical microprocessors like the Intel Core family or Pentium family.



processors or similar processors are in computers as a general purpose programmable device. In its lifeperiod it has to handle many different tasks and programs given to it. On the other hand a micro controllers from 8051 family or PIC family or any other have found there applications in small embedded systems like some kind of robotic system or a traffic signal control system. Also these devices handle same task or same program during there complete life cycle. (Best example is of traffic signal control system). The other difference is that the micro controllers usually has to handle real time tasks while on the contrary the microprocessors in a computer system may not handle a real time task at all times.

Salient features of 80286?

Produced From 1982 to early 1990s

Max. CPUclock rate 6 MHz (4 MHz for a short time) to 25 MHz

Instruction set x86-16 (with MMU)

Predecessor Intel 80186 Successor Intel 80386 Intel 80287 Co-processor

 68-pin PLCC 100-pin PQFP Package(s) 68-pin PGA

The Intel80286 ("eighty-two-eighty-six"; also called the iAPX 286, "two-eighty-six"), introduced on 1 February 1982, was a 16-bitx86microprocessor with 134,000 transistors. Like its contemporary simpler cousin, the 80186, it could correctly execute most software written for the earlier Intel 8086 and 8088. It was employed for the IBM PC/AT, introduced in 1984, and then widely used in most PC/AT compatible computers until the early 1990s. The 80286 was the first x86 microprocessor with memory management and wide protection abilities. The 80286 was designed for multi-user systems with multitasking applications, including communications (such as automated PBXs) and real-timeprocess control. It had 134,000 transistors and consisted of four independent units: address unit, bus unit, instruction unit and execution unit, which formed a pipeline significantly increasing the performance. It was produced

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The intel 80286 had a 24-bit address bus and was able to address up to 16 MB of RAM, compared to 1 MB for its predecessor. However cost and initial rarity of software using the memory above 1 MB meant that 80286 computers were rarely shipped with more than onemegabyte of RAM. Additionally, there was a performance penalty involved in accessing extended memory from real mode

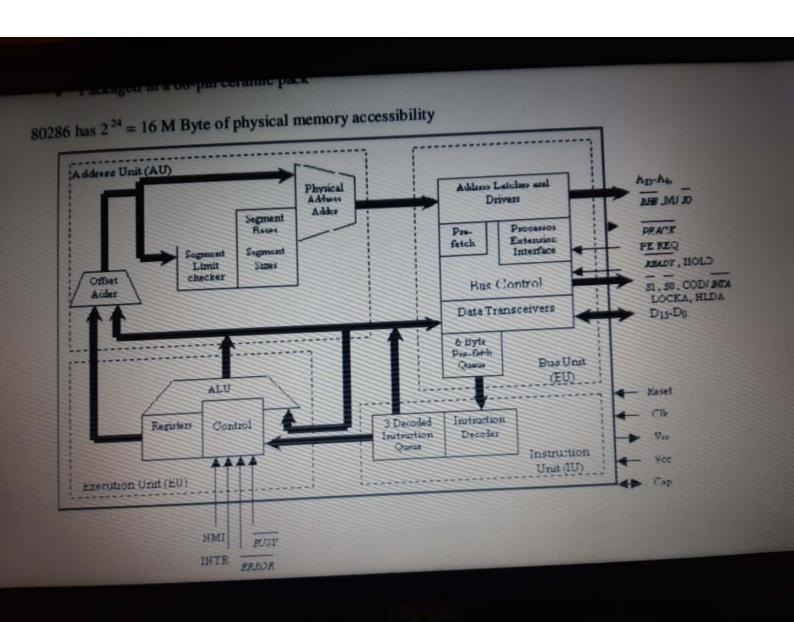
Internal architecture of 80286?

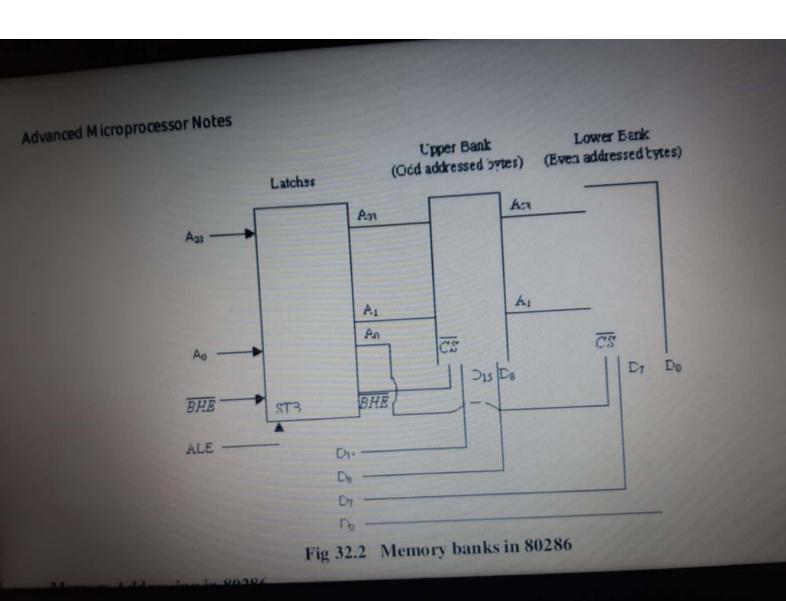
Key Features -

- · 16-bit date bus
- · 24-bit non-multiplexed bus
- · Packaged in a 68-pin ceramic pack

80286 has $2^{24} = 16$ M Byte of physical memory accessibility

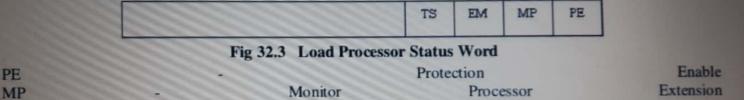






Memory Addressing in 80286

- Real Addressing Mode It is just like as in 8086. Address is 20 bit with 16 bit segment and 16 bit offset. When 80286 is hardware reset, it automatically enters real address mode.
- Protected Virtual Addressing Mode (PVAM) In this we have 1 GByte of virtual memory and 16
 Mbyte of physical memory. The address is 24 bit. To enter PVAM mode, Processor Status Word
 (PSW) is loaded by the instruction LPSW.



Processor

TS - Task Switch

EM

Hardware reset is the only way to come out of protected mode.

80286 Memory Management Scheme

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Memory is organized into logical segments. Segment size can be anywhere between 1 Byte to 16 KByte. All 24 address pins are active and 16 MByte of physical memory is available.

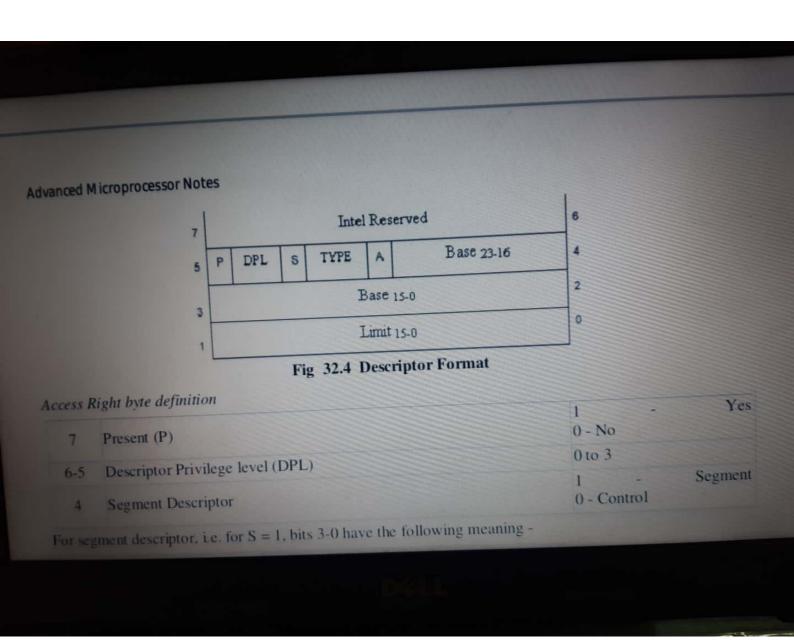
Descriptor

It is 8-byte quantity. Each segment has a descriptor. There are two main types of descriptor -

Emulate

- Segment Descriptor
- System control Descriptor

Extension



0 - Control

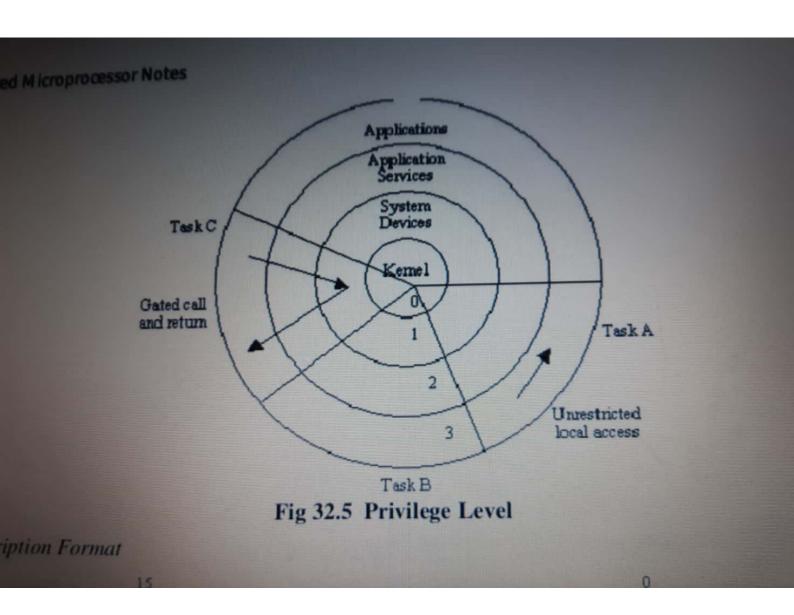
seg	ment descriptor, i.e. fo	or S = 1, bits 3-0 have the following meaning Data			
3	Е	1 - Code			
2	case)				
1	R/W	If code, Readable: 1 - Yes, 0 - N If data, Writeable: 1 - Yes, 0 - Not			
0	Accessed (A)	A = 0, Not accessed			

Descriptors are contained in a descriptor table. There are two categories of descriptor table - global and local. A system has only one global descriptor table or GDT. A local descriptor table or LDT is set up in the system for each task or closely related group of tasks. Each task can have its own descriptor table and memory area defined by the descriptors in it.

Accessing Segments

The 80286 microprocessor keeps the base address and limits for the descriptor tables currently in use in internal registers. These registers are load descriptor table register (LDTR) and global descriptor table register (GDTR). Descriptor in memory is addressed by adding segment selector to these registers. The descriptors contain the base address of segments, which when added with the offset in the virtual address points to the required memory location.

Accessing a Segment of Higher Privilege Level



Gate Description Format

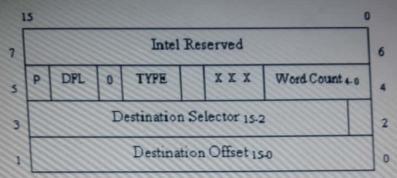


Fig 32.6 Gate Descriptor Format

Name	Value	Description	
Type	4	Call gate	
	5	Task gate	
	6	Interrupt gate	
	7	Trap gate	
P	0	Descriptor contents are NOT valid	
	MILLER	Descriptor contents are valid	
DPL	0-3	Descriptor privilege level	
Word Count	0-31	Number of words to copy from callers stack to called procedures stack. Only used with called gates.	

		Descriptor contents are valid		
DPL	0-3	Descriptor privilege level		
Word Count	0-31	Number of words to copy from callers stack to called procedures stack. Only used with called gates. Selector to target code segment (call, interrupt, task gates) Selector to target task state segment (task gate)		
Destination Selector	16-bit Selector			
Destination Offset 16-bit Offset		Entry point within the target code segment		

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Each task in a PVAM system has a 22-word task state segment (TSS) associated with it. A TSS holds copies of all registers and flags, the selector for the tasks' LDT, and a link to the TSS of the previously executing task.

Descriptors for each task state segment are kept in the global descriptor table. A task register (TR) in the 80286 holds the selector and the task state segment descriptor for the currently executing task. The load task register (LTR) instruction can be used to initialize the task register to the task state segment for a particular task. During a task switch the task register is automatically loaded with the selector and descriptor for the new task.

Method of Task Switching

- 1. Long jump or call instructions that contain a selector which points to the Task State segment descriptor
- 2. IRET
- 3. Selectors in a long jump or call points to a task gate
- 4. Interrupt occurs and the vectors point to a task gate descriptor

Real addressing mode has 256 interrupts with types 0-255. Each interrupt takes 4 bytes, so we have to reserve 1KByte of memory for interrupt.

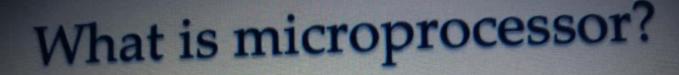
In PVAM mode also we have 256 interrunts but it is not assigned a fixed memory. The interrunt descriptor

4. Interrupt occurs and the vectors point to a task gate descriptor

Real addressing mode has 256 interrupts with types 0-255. Each interrupt takes 4 bytes, so we have to reserve 1KByte of memory for interrupt.

In PVAM mode also we have 256 interrupts but it is not assigned a fixed memory. The interrupt descriptor table can be anywhere in the physical memory. Base address of interrupt descriptor table is stored in interrupt descriptor table register (IDTR). The particular descriptor is accessed as follows -(Interrupt Type * 8) + IDTR → Descriptor





The microprocessor is a multipurpose, programmable device that accepts digital data as input, processes it according to instructions stored in it's memory and provide results as output.

It is an example of digital logic and it uses binary and hexadecimal numerical systems

Intel 80286 microprocessor

- Introuduced in 1982
- 5th of i86 family
- Faster clock speed than previous versions (12.5 MHz clock speed vs 10MHz)
- 16-bit microprocessor as like 8086
- 125K transistors, HMOS III technology
- Advanced Memory management
- Multitasking Ability
- Better Pipelining method
- 4 independent functional unit in internal architecture



Comparison of 80286 among some other microprocessors of Intel family

Microprocessor	Data bus width	Address bus width	Memory size
8086	16	20	1M
80186	16	20	1M
80286	16	24	16M
80386 DX	32	32	4G
80486	32	32	4G
Pentium 4 & core 2	64	40	1T

80286 Salient features

- Two mode of operation
- More Addressable Memory
- Virtual Memory in Protected Mode

Feature 1: Operating Modes

Intel 80286 has 2 operating modes.

- Real address mode.
- 2. Protected Virtual address mode.
 - Real Address Mode :
 - > 80286 just act as a faster version of 8086
 - And program for 8086 can be executed without modification in 80286
 - Protected Virtual Address Mode:
 - 80286 supports multitasking
 - Able to run several program at the same time
 - Able to protect memory space for another program

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Feature 2: More Addressable Memory

- In protected mode 80286 can address 16 megabytes of physical memory
- Where 8086 can address only 1 megabyte

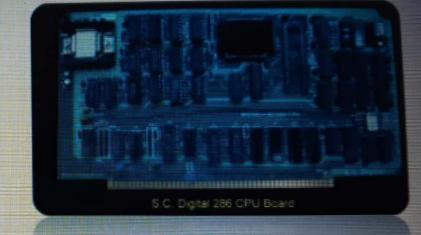
Feature 3: Virtual Memory in Protected Mode

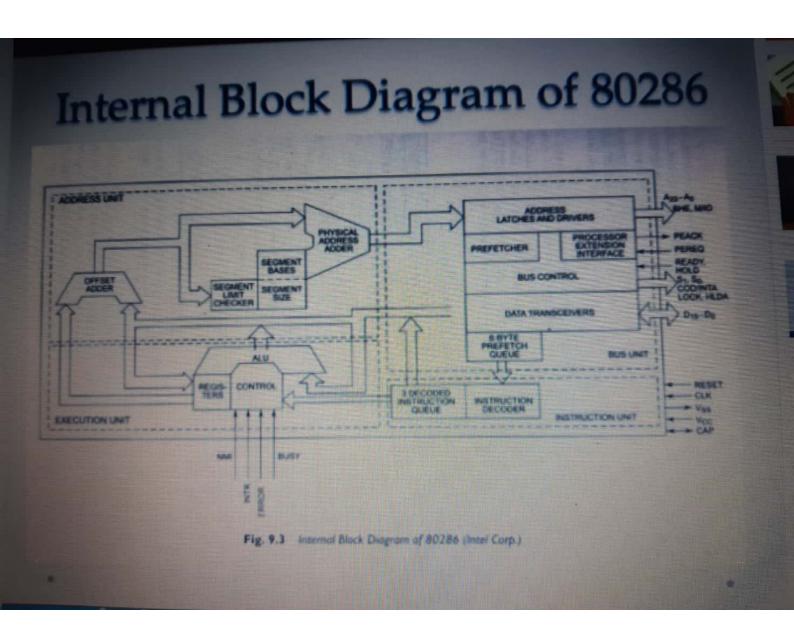
- 80286 can treat external storage as it were physical memory
- Execute programs that are too large to be contained in physical memory
- Program can be upto 2³⁰ bytes

Functional Parts

- 1. Address unit
- 2. Bus unit
- 3. Instruction unit
- 4. Execution unit

Where 8086 has only two functional parts





Register organization of 80286

The 80286 CPU contains almost the same set of registers, as in 8086.

- 1. Eight 16-bit general purpose registers.
- 2. Four 16 bit segment registers.
- 3. Status and control register.
- 4. Instruction pointer.

